

CASH FLOW MATCHING WITH RISKS CONTROLLED BY bPOE AND CVaR

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Outline

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- 3 Portfolio Optimization with bPOE and CVaR
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- 5 Case Study using Portfolio Safeguard (PSG)

Deterministic Cash Flow Matching Problem

$\{1, \dots, M\}$ = set of considered bonds

$p_0 = (p_0^1, \dots, p_0^M)$ = vector of initial prices of bonds

$x_0 = (x_0^1, \dots, x_0^M)$ = vector of bond positions

$c_t = (c_t^1, \dots, c_t^M)$ = cash flow vector at time t

l_t = liability at time t

$S_t(x_0)$ = shortage at time t

Minimizing initial cost s.t. constraints for shortages

$$\min_{x_0} (p_0, x_0)$$

subject to

$$S_t(x_0) = l_t - (c_t, x_0) \leq 0, \quad t = 1, \dots, T,$$
$$x_0 \geq 0.$$

Stochastic Cash Flow Matching Problem

Iyengar and Ma (2009)

p_t = random price vector for bonds at time $t = 1, \dots, T$

x_t = vector of bond positions purchased at time t

$c_{s,t}$ = c.f. vector at time t from bonds purchased at time s

$S_t(x_0, \dots, x_t)$ = random shortage at time t :

$$S_t(x_0, \dots, x_t) = (p_t, x_t) + l_t - \sum_{s=0}^{t-1} (c_{s,t}, x_s), \quad t = 1, \dots, T.$$

$L(x_0, \dots, x_T)$ = random maximum shortage (Loss) over all time periods:

$$L(x_0, \dots, x_T) = \max_{0 \leq t \leq T} S_t(x_0, \dots, x_t).$$

Stochastic Cash Flow Matching Problem

Iyengar and Ma (2009) - CVaR in Constraint with different α

$$\begin{aligned} & \min_{x_0, \dots, x_T} (p_0, x_0) \\ & \text{subject to} \\ & CVaR_\alpha(L(x_0, \dots, x_T)) \leq 0, \\ & x_t \geq 0, \quad t = 0, \dots, T. \end{aligned}$$

Problem statement with abstract Risk function

$$\begin{aligned} & \min_{x_0, \dots, x_T} (p_0, x_0) \\ & \text{subject to} \end{aligned}$$

Risk controlled by Risk function depending on Loss $L(x_0, \dots, x_T)$

$$x_t \geq 0, \quad t = 0, \dots, T.$$

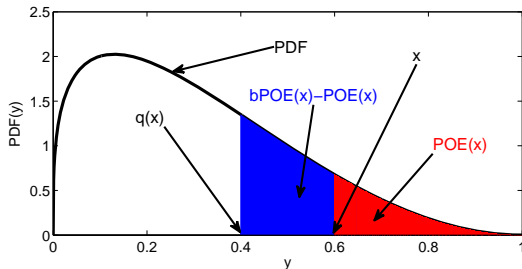
Buffered Probability of Exceedance (bPOE)

$$\underline{POE = P(X > x)}$$

Let $q(x)$ is defined by $E[X|X > q(x))] = x$

bPOE = $P(X > q(x))$, “Buffer” = $x - q(x)$

$$CVaR_{\alpha}(L) \geq VaR_{\alpha}(L); \quad bPOE_z(L) \geq POE_z(L)$$



bPOE: (Mafusalov & U and Norton & U, 2014)

Lower bPOE

$$bPOE_z^-(L) = \begin{cases} 0, & \text{for } z \geq \sup L; \\ 1 - \{\alpha \mid CVaR_\alpha(L) = z\}, & \text{for } E[L] < z < \sup L; \\ 1, & \text{for } z \leq E[L]. \end{cases}$$

Upper bPOE

$$bPOE_z^+(L) = \begin{cases} 0, & \text{for } z > \sup L; \\ 1 - \{\alpha \mid CVaR_\alpha(L) = z\}, & \text{for } E[L] < z \leq \sup L; \\ 1, & \text{for } z \leq E[L]. \end{cases}$$

$$bPOE_z^+(L) = \min_{\lambda \geq 0} E[\lambda(L - z) + 1]^+.$$

Example: CVaR and bPOE for 3 scenarios

We work with Upper bPOE and just write $bPOE_z(L)$

$$CVaR_\alpha(L) \geq VaR_\alpha(L); \quad bPOE_z(L) \geq POE_z(L)$$

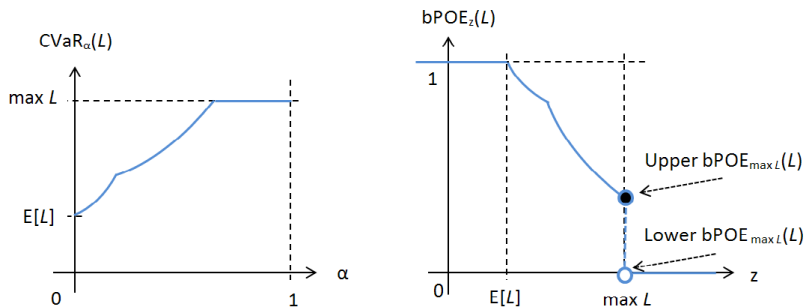


Figure: CVaR and bPOE for random Loss L with 3 scenarios.

CVaR vs bPOE in Constraint

$$\begin{aligned} \min_{x_0, \dots, x_T} \quad & (p_0, x_0) \\ \text{subject to} \quad & \\ & CVaR_\alpha(L) \leq z, \\ & x_t \geq 0, \quad t = 0, \dots, T. \end{aligned}$$

Direct controlling probability of maximum shortage with bPOE

$$\begin{aligned} \min_{x_0, \dots, x_T} \quad & (p_0, x_0) \\ \text{subject to} \quad & \\ & bPOE_z(L) \leq 1 - \alpha, \\ & x_t \geq 0, \quad t = 0, \dots, T. \end{aligned}$$

CVaR vs bPOE in Objective

$$\begin{aligned} \min_{x_0, \dots, x_T} \quad & CVaR_\alpha(L) \\ \text{subject to} \quad & (p_0, x_0) \leq d, \\ & x_t \geq 0, \quad t = 0, \dots, T. \end{aligned}$$

Direct minimizing probability of maximum shortage with bPOE

$$\begin{aligned} \min_{x_0, \dots, x_T} \quad & bPOE_z(L) \\ \text{subject to} \quad & (p_0, x_0) \leq d, \\ & x_t \geq 0, \quad t = 0, \dots, T, \end{aligned}$$

Equivalence of CVaR and bPOE Constraints

Problems with CVaR and Lower bPOE constraints are equivalent.

Problems with CVaR and (Upper) bPOE constraints are "near" equivalent:

Constraint on bPOE implies constraint on CVaR.

$$bPOE_z(L) \leq 1 - \alpha \Rightarrow CVaR_\alpha(L) \leq z$$

Constraint on CVaR implies constraint on bPOE.

$$\text{Let } y > z, \text{ then } CVaR_\alpha(L) \leq z \Rightarrow bPOE_y(L) < 1 - \alpha$$

bPOE Minimization => Convex Programming

$S_t = (a_t, x) + b_t =$ random function of decision vectors x

$$\begin{aligned}\min_x bPOE_z(L) &= \min_x \min_{\lambda \geq 0} E[\lambda(\max_{0 \leq t \leq T} S_t - z) + 1]^+ \\ &= \min_{\lambda \geq 0, x} E[\lambda(\max_{0 \leq t \leq T} \{(a_t, x) + b_t\} - z) + 1]^+ \\ &= \min_{\lambda \geq 0, x} E[\max_{0 \leq t \leq T} \{(a_t, \lambda x) + \lambda(b_t - z)\} + 1]^+.\end{aligned}$$

Change of variables: $(\lambda x, \lambda) \rightarrow (y, \lambda)$

$$\min_x bPOE_z(L) = \min_{\lambda \geq 0, y} E[\max_{0 \leq t \leq T} D_t(\lambda, y, z) + 1]^+,$$

$D_t(\lambda, y, z) = (a_t, y) + \lambda(b_t - z) =$ random linear function of vector y and variable λ with parameter z .

bPOE Minimization \Rightarrow Convex Programming

Change of variables: $(\lambda x, \lambda) \rightarrow (y, \lambda)$

$$S(x) = (a, x) + b \rightarrow D(\lambda, y, c) = (a, y) + \lambda(b - c)$$

Constraints transformation

Linear: $C_l \leq Ax \leq C_u \rightarrow C_l \lambda \leq Ay$ and $Ay \leq C_u \lambda$

Quadratic: $(x, Qx) \leq c \rightarrow (y, Qy) \leq c\lambda^2$

Cvar: $CVaR_\alpha(S(x)) \leq c \rightarrow CVaR_\alpha(D(\lambda, y, 0)) \leq c\lambda$

Partial Moment: $PM_z(S(x)) \leq c \rightarrow PM_0(D(\lambda, y, z)) \leq c\lambda$

Direct minimizing bPOE in new space using LP

$$\min_{\lambda \geq 0, y} E[\max_{0 \leq t \leq T} D_t(\lambda, y, z) + 1]^+ = \min_{\lambda, y} PM_{-1}(\max_{0 \leq t \leq T} D_t(\lambda, y, z))$$

$$(p_0, y_0) - d\lambda \leq 0,$$

$$\lambda \geq 0, \quad y_t \geq 0, \quad t = 0, \dots, T.$$

bPOE Minimization \Rightarrow Linear Programming

LP with additional variables $u_k, k = 1, \dots, K$ corresponding to scenarios of $L(x_0, \dots, x_T)$:

$$\min_{\lambda, y, u} \sum_{k=1}^K p_k u_k$$

subject to

$$u_k \geq (a_t^k, y_t) + \lambda(b_t^k - z) + 1, \quad t = 0, \dots, T, \quad k = 1, \dots, K,$$
$$(p_0, y_0) - d\lambda \leq 0,$$

$$\lambda \geq 0, \quad y_t \geq 0, \quad t = 0, \dots, T, \quad u_k \geq 0, \quad k = 1, \dots, K.$$

Restoring x_t : If $\lambda^* > 0$ then $x_t^* = y_t^* / \lambda^*$;

If $\lambda^* = 0$ then $bPOE_z(L) = E[\lambda^*(L - z) + 1]^+ = 1$ for any feasible x_0, \dots, x_T .

Case study: Data and Problems Size

$T = 120$ time periods with 0.5 year length;

$K = 200$ simulations (scenarios) of bond prices;

$M = 11$ number of available bonds;

Stream of liabilities (like in: Iyengar and Ma (2009))

$$l_t = \begin{cases} 100 & \text{if } t/2 = 0, \dots, 10, \\ 110 - 2.2 \times (\frac{t}{2} - 10) & \text{if } t/2 = 11, \dots, 60, \\ 0 & \text{otherwise.} \end{cases}$$

1331 = number of variables in optimization problems;

24201 = number of constraints in LP problem.

Case study: Details of Treasury Bonds

Bond	Name	Maturity	Coupon Rate (%)	Current Price
1	T-bill	0.5	0	95.8561
2	T-note	1	4.5	96.1385
3	T-note	2	4.5	92.6873
4	T-note	3	4.5	89.5784
5	T-note	4	4.5	86.7610
6	T-note	5	4.5	84.1959
7	T-bond	10	5.0	77.5948
8	T-bond	15	5.0	71.9232
9	T-bond	20	5.0	68.1357
10	T-bond	25	5.0	65.5990
11	T-bond	30	5.0	63.8989

Optimization using Portfolio Safeguard (PSG)

$$\begin{aligned} \min_{x_0, \dots, x_T} \quad & bPOE_z(L) \\ \text{subject to} \quad & (p_0, x_0) \leq d, \\ & x_t \geq 0, \quad t = 0, \dots, T. \end{aligned}$$

Problem statement in PSG

minimize

linearize =1

bPOE(0,Lmax(matrix_1,...,matrix_120))

Constraint: <= 1172.368

linear(matrix_0)

Box: >= 0

Solver: cargrb

Solution obtained by Portfolio Safeguard (PSG)

Solution_problem_cash_flow_matching_3.txt

Problem: solution_status = optimal

Variables: optimal_point = point_problem_cash_flow_matching_3

Objective: = 0.1000000000062

Constraint: constraint_1 = 0.0 [0.0]

Function: bpoe(0,lmax(matrix_1,...,matrix_120)) = 0.10000000000053

Function: linear(matrix_0) = 1172.368

Point_problem_cash_flow_matching_3.txt

	Component_name	Value
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x0_1	0.000000000000e+00
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x0_2	1.837109350078e-01
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x0_3	2.078663430491e-01
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x0_4	2.272771609577e-01
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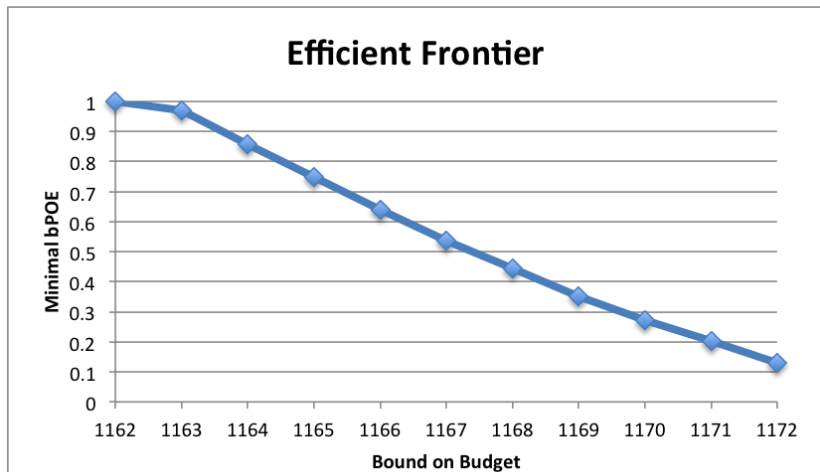
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x120_10	0.000000000000e+00
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x120_11	0.000000000000e+00
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Efficient frontier

Four optimization problems generate "almost" the same efficient frontiers for $bPOE_0(L(x_0, \dots, x_T))$ and (p_0, x_0) .



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